

# One-bit Compressed Sensing: Provable Support and Vector Recovery

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# Compressed Sensing

$$y = Ax$$

$M \times 1$ 
 $M \times N \ (M < N)$ 
 $N \times 1^1$

- Goal: Reconstruct a sparse signal using very few linear measurements
- Tremendous amount of work in the last decade
- $O(k \log n)$  measurements to reconstruct  $k$ -sparse signals in  $\mathbb{R}^n$

<sup>1</sup><http://lions.epfl.ch/research>

# Quantization

- Measurements up to infinite precision - not practical
  - $y_j = -1.010001011110$
- Arbitrary quantization does not work well [BB08]
  - $y_j = -1.01$
- Extreme quantization - single bit measurements
  - $y_j = -1$

# One-bit Compressed Sensing [BB08]

Goal: Reconstruct a sparse signal using signs of very few linear measurements

$$y = \text{Sign}(Ax)$$

$M \times 1$ 
 $M \times N (M < N)$ 
 $N \times 1$

- Formally, given  $y$  and  $A$ , recover  $x$
- Motivation:
  - Captures extreme quantization
  - Easy to implement
  - Robust to noise

# Frameworks

Exact recovery not possible:

For example,  $y = \text{Sign}(Ax) = \text{Sign}(A(cx)), \forall c > 0$

## Frameworks

- Support recovery: recover  $\hat{x}$  such that

$$\text{Supp}(x) = \text{Supp}(\hat{x})$$

- $\epsilon$ -approximate recovery<sup>a</sup>: recover  $k$ -sparse  $\hat{x}$  such that

$$\left\| \hat{x} - \frac{x}{\|x\|} \right\| < \epsilon$$

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<sup>a</sup> $\|\cdot\|$  refers to two norm

# Metrics

- Measurement (or sample) complexity: dimension of  $y$
- Computational complexity: time taken by the recovery algorithm
- Universality: use the same measurement matrix  $A$  for all sparse vectors  $x$ 
  - critical for many applications e.g., single pixel camera

# Our Results – Support Recovery

Algorithm	[HB11]	UFF	Expanders
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Universal	No	Yes	Yes
-ve entries allowed?	Yes	No	Yes
# measurements	$O(k \log n)$	$O(k^2 \log n)$	$O(k^3 \log n)$
Running Time	$O(n \log n)$	$O(nk \log n)$	$O(nk \log n)$

- *First universal* measurement schemes
- Open problem:  $O(k \log n)$  universal measurement scheme not known

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for all distinct  $B_{i_0}, B_{i_1}, \dots, B_{i_k} \in \mathcal{F}$ .

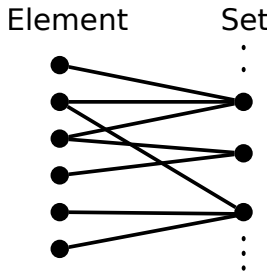
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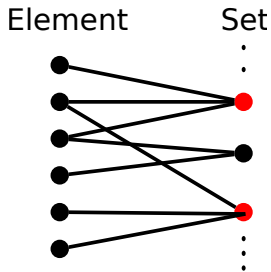
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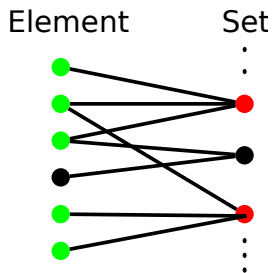
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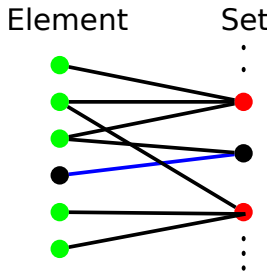
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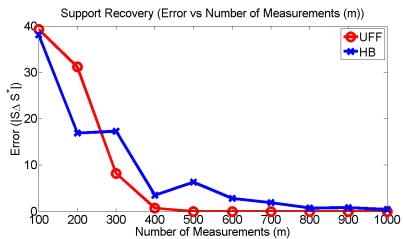
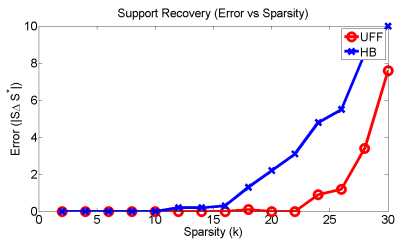
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- Well studied combinatorial objects
- Use their structure in the measurement scheme *and* recovery algorithm
- Works for  $x \geq 0$ 
  - Another algorithm based on expanders, which works for any  $x$

# Experiments



# $\epsilon$ -approximate recovery

- Recall: Need to recover  $\hat{x}$  such that  $\left\| \hat{x} - \frac{x}{\|x\|} \right\| < \epsilon$
- Plan and Vershynin [PV11, PV12]:  $O(\epsilon^{-5})$  measurements
  - hard thresholding and soft thresholding based approaches
- Our result:  $\tilde{O}(\epsilon^{-1})$  measurements
- Key idea: Combine optimal results from compressed sensing and learning halfspaces

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Algorithm	[PV11, PV12]	Two-stage	S-Approx
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# Our Results – Approximate Recovery

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Universal	Yes	Yes	Yes
# measurements ( $m$ )	$\frac{k}{\epsilon^5} \log^2 \frac{n}{k}$	$\frac{k}{\epsilon} \log \frac{n}{k}$	$k^3 \log \frac{n}{k} + \frac{k}{\epsilon}$
Running Time	$\frac{kn}{\epsilon^6} \log \frac{n}{k}$	$\frac{kn}{\epsilon^5} \log \frac{n}{k}$	$\frac{k^5 n}{\epsilon^5} \log \frac{n}{k}$

- Two-stage: *Near optimal* measurement complexity

# Measurement Scheme and Algorithm

$$y = \text{Sign}(\overbrace{A_2 A_1}^A x)$$

Random Gaussian Matrix      Compressed Sensing Matrix



# Measurement Scheme and Algorithm

$$y = \text{Sign}(\overbrace{A_2 A_1}^A x)$$

Random Compressed  
Gaussian Sensing  
Matrix Matrix

## Algorithm

- 1 Linear programming: Obtain  $\hat{z}$  such that  $y = \text{Sign}(A_2 \hat{z})$

# Measurement Scheme and Algorithm

$$y = \text{Sign}(\overbrace{A_2 A_1}^A x)$$

Random Compressed  
Gaussian Sensing  
Matrix Matrix

## Algorithm

- 1 Linear programming: Obtain  $\hat{z}$  such that  $y = \text{Sign}(A_2 \hat{z})$
- 2 Solve CS problem:  $\hat{z} = A_1 x + e$  (GraDeS [GK09])

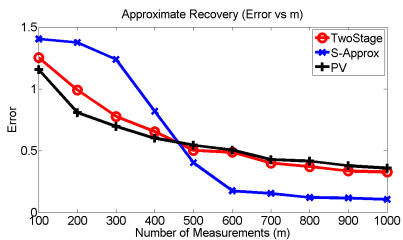
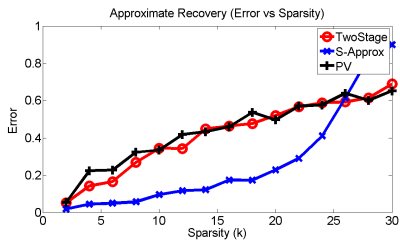
# Proof Outline

$$y = \underset{\parallel}{\text{Sign}}(A_2 z)$$

$$A_1 x$$

- 1 Robust CS: sufficient to obtain  $\hat{z}$  such that  $\|\hat{z} - z\| < C\epsilon$ .
  - requires  $O(k \log n)$  measurements
- 2 Obtain  $\hat{z}$ : requires  $O\left(\frac{k \log n}{\epsilon} \log\left(\frac{k \log n}{\epsilon}\right)\right)$  random Gaussian measurements.

# Experiments



# Summary

- One-bit Compressed Sensing
  - captures extreme quantization
  - several other motivations
- Support recovery
  - *First universal* measurement schemes using UFF and expanders
  - UFF:  $O(k^2 \log n)$  measurements but for  $x \geq 0$ 
    - Can be used in other settings?
  - Expanders:  $O(k^3 \log n)$  measurements for any  $x$
  - **Open question**: achieving  $O(k \log n)$  sample complexity
- $\epsilon$ -approximate recovery
  - *Near optimal* sample complexity with  $\epsilon$
  - Support recovery based algorithm - works well empirically

# References



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